

About...

Specter :

- * An entity of service
- * Enjoys reversing black-box hardware



About...

Specter :

- * An entity of service
- * Enjoys reversing black-box hardware
- * **Heating Engineer**



Play video1.mp4

Stephen Chavez introduces
Himself in SAS2017 clip

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BOX CEO Aaron Levie Talks Trump, Tech, And How To Stay Nimble As A Public Software Company

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AUG 6, 2016 @ 03:50 PM 2,757

The Little Black Book of Billionaire

This Guy Let Me Control His Hacked Wheelchair With An Xbox Gamepad



Thomas Fox-Brewster, FORBES STAFF

I cover crime, privacy and security in digital and physical forms. [FULL BIO](#)



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BOX CE Talks Tr How To Public S

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GeekPwn 2016, Shanghai

k of Billionaire

Xbox

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iPhone 7

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Kaspersky SAS 2017

WHAT IS R-NET/CANBUS?

R-NET Protocol

- On-the-fly-configuration
- Advanced motor control algorithms
- Uses special ID's to allow chair modules to act on certain messages

CAN BUS (Controller Area Network)

- Vehicle protocol standard
- Network based
- Any device on the same CAN BUS network can send/receive CAN messages
- Has no security/authentication
 - Inject our own messages

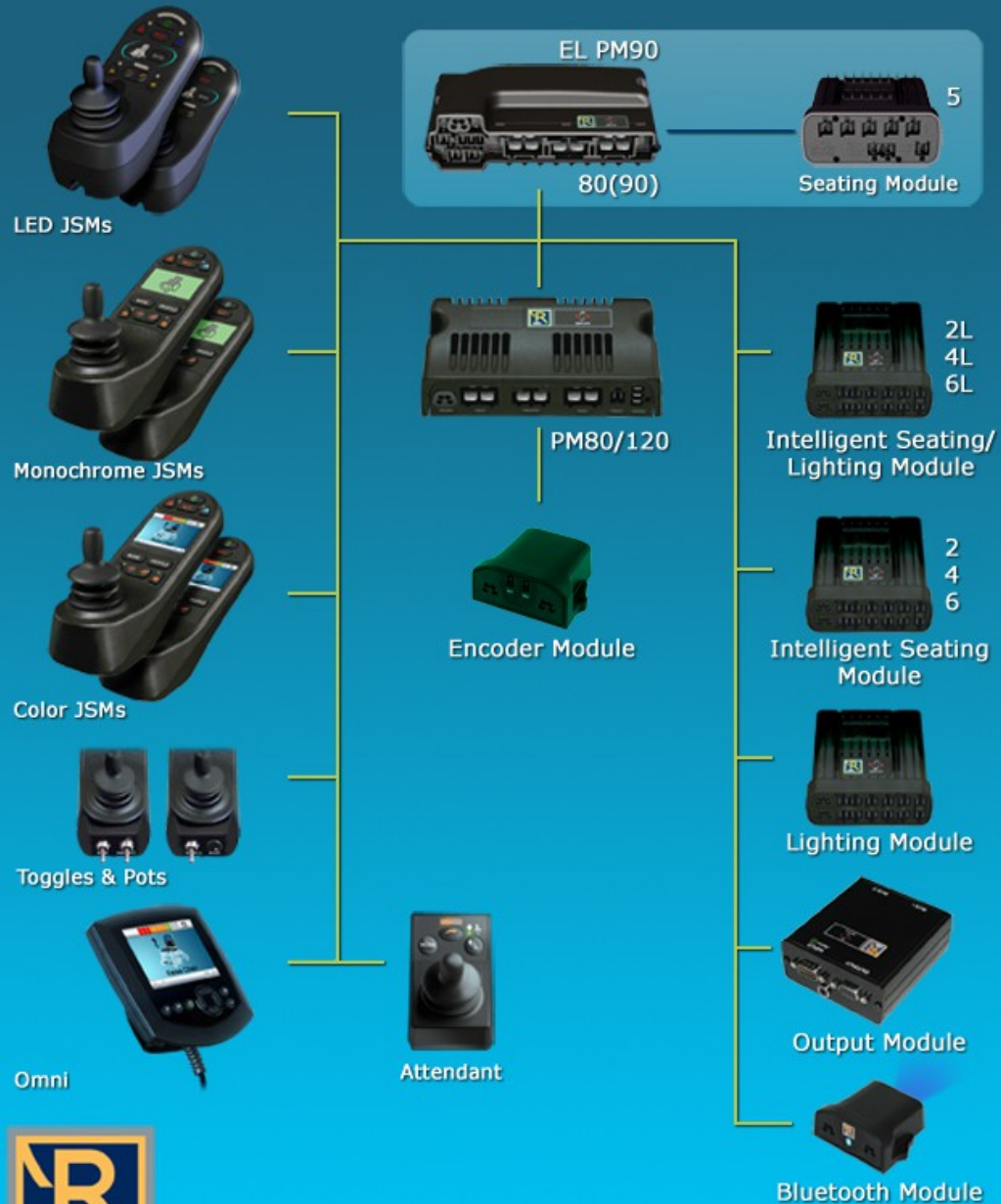
Security Analyst Summit 2017



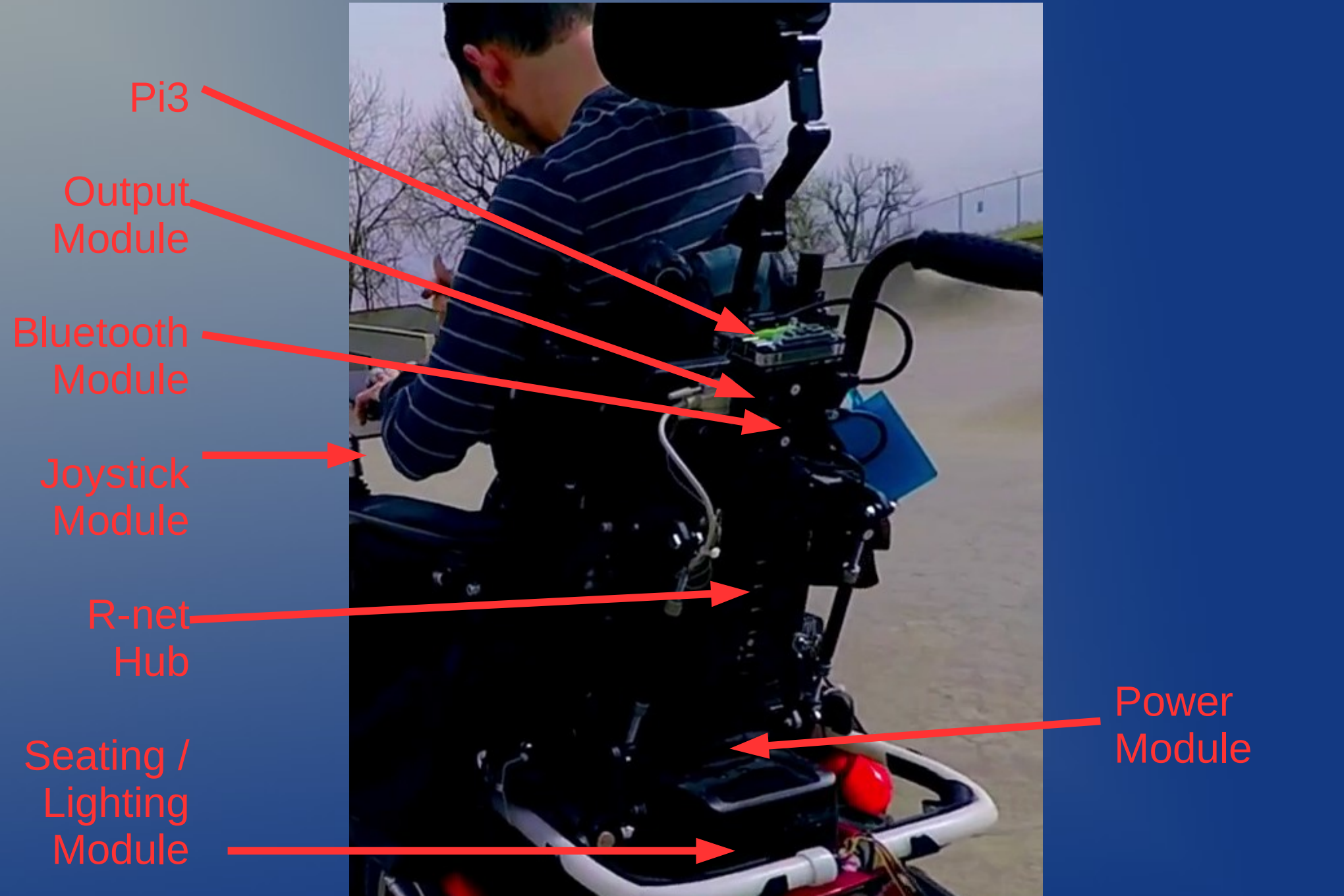
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R-net devices



The R-net Family



Pi3

Output
Module

Bluetooth
Module

Joystick
Module

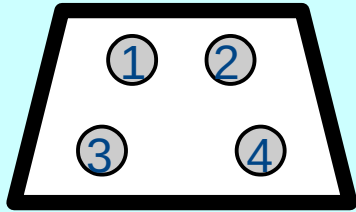
R-net
Hub

Seating /
Lighting
Module

Power
Module

R-Net interface and topology

Female / Device side



- 1) CAN Lo
- 2) CAN Hi
- 3) +24VDC
- 4) GND(-)

PM



Hub



Pi3 + PiCan2



R-NET rides on CANBUS 2.0B

Differential pair. Dominant and recessive bits.

dominant is a logical 0 (actively driven to a voltage by the transmitter)
recessive is a logical 1 (passively returned to a voltage by a resistor)

Frame oriented. IDs: 11bits(standard frame)

11+18bits(extended frame). Data can be 0 to 8 bytes.

Speeds: R-net is at 125Kbps. Max 1Mbps for Can 2.0B

FrameID represents message priority.

If multiple messages attempt to xmit at the same time, the lowest ID wins.

Protocol chips do the work.

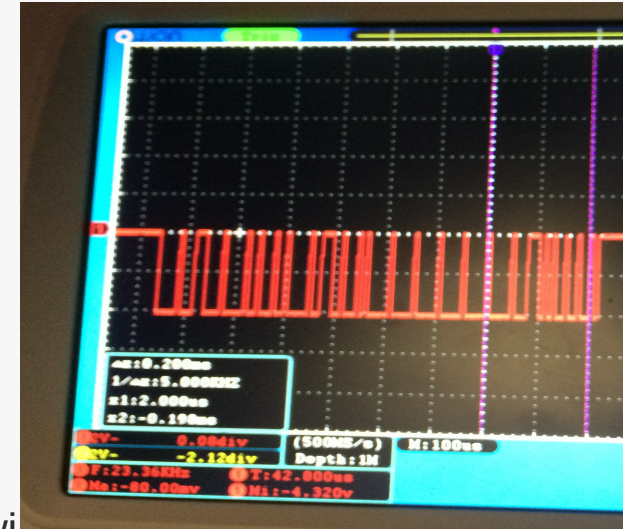
CAN protocol is built in to many SOCs (Beaglebone) and MCUs(ARM Cortex M3/M4.)

Acknowledge bit (@ end of frame) is set by any receiving device.

Errors in transmission can be instantly detected. We tried bit banging to kill frames.
This instantly causes an error condition and the frame is resent (no timeout).

There are no addresses implicit in CAN protocol.

This makes it difficult to determine what is source/destination.



R-NET CAN frame examples

Horn beep:

```
$ cansend can0 0C040100# ;sleep .2; cansend can0 0c040101#
```

Set maximum power to 50%:

```
$ cansend can0 0A040100#32; cansend can0 181c0100#0260000000000000
```

Random battery levels:

```
$ cangen can0 -l 1C0C0100 -L 1 -e -g 100
```

Change from mode "0" to mode "1":

```
$ cansend can0 061#40400000; sleep .1; cansend can0 061#00410000
```

*can0 [Wireshark 1.12.1 (Git Rev Unknown from unknown)]

File Edit View Go Capture Analyze Statistics Telephony Tools Internals Help

Filter: Expression... Clear Apply Save jsm_heartbeats

No.	Time	Length	Info
315	2.837178000	10	XTD: 0x02000100 00 00
316	2.847196000	10	XTD: 0x02000100 00 00
317	2.857223000	10	XTD: 0x02000100 00 00
318	2.861375000	10	XTD: 0x14300000 00 00
319	2.867185000	10	XTD: 0x02000100 00 00
320	2.871171000	16	STD: 0x0000000e 08 90 1c 8a 00 00 00 00
321	2.877192000	10	XTD: 0x02000100 00 00
322	2.887183000	10	XTD: 0x02000100 00 00
323	2.897281000	10	XTD: 0x02000100 00 00
324	2.898273000	15	XTD: 0x03c30f0f 87 87 87 87 87 87 87
325	2.907235000	10	XTD: 0x02000100 00 00
326	2.911412000	8	XTD: 0x0c000000
327	2.911838000	16	XTD: 0x1c300004 6c b0 4d 00 6c b0 4d 00
328	2.920997000	16	STD: 0x0000000e 08 90 1c 8a 00 00 00 00
329	2.954035000	13	XTD: 0x1c200100 04 81 00 00 03
330	2.971239000	16	STD: 0x0000000e 08 90 1c 8a 00 00 00 00
331	2.997445000	15	XTD: 0x03c30f0f 87 87 87 87 87 87 87
332	3.020994000	16	STD: 0x0000000e 08 90 1c 8a 00 00 00 00
333	3.071271000	16	STD: 0x0000000e 08 90 1c 8a 00 00 00 00
334	3.097462000	15	XTD: 0x03c30f0f 87 87 87 87 87 87 87
335	3.111383000	9	XTD: 0x0c140000 c0
336	3.112096000	10	XTD: 0x14300000 00 00
337	3.120962000	16	STD: 0x0000000e 08 90 1c 8a 00 00 00 00
338	3.171285000	16	STD: 0x0000000e 08 90 1c 8a 00 00 00 00
339	3.197629000	15	XTD: 0x03c30f0f 87 87 87 87 87 87 87
340	3.211508000	9	XTD: 0x0c140000 01
341	3.221085000	16	STD: 0x0000000e 08 90 1c 8a 00 00 00 00
342	3.271308000	16	STD: 0x0000000e 08 90 1c 8a 00 00 00 00
343	3.297535000	15	XTD: 0x03c30f0f 87 87 87 87 87 87 87
344	3.321005000	16	STD: 0x0000000e 08 90 1c 8a 00 00 00 00
345	3.361643000	10	XTD: 0x14300000 00 00
346	3.371265000	16	STD: 0x0000000e 08 90 1c 8a 00 00 00 00

JSMerror exploit

Green = JoyXY frames
 Yellow = JSM heartbeats
 Red = Injected frame

JSM is in “drive” mode
 Outputs JoyXY frames...
 until a JSM network error is triggered.

JSM continues to output heartbeat frames but stops outputting JoyXY frames.
 At the point of error we can take up the rhythm with injection.

Synchronizing our spoofed JoyXY frames may be done by clocking the last JSM JoyXY frame prior to inducing the JSM error.

Reversing R-NET

STARTUP and NETWORK CONFIG frames:

```
000#R          :PMtx sleep all devices
002#R          :PMtx sleep all devices
00C#          :JSMtx test canbus connection. Checks for ack on bus prior to JSM wake
04M#00000000  :JSMrx select modemap M for parameter exchange. See: 78M#... causes
04M#80000000  :JSMtx end parameter exchange for mode M.
7B3#          :PMtx global request for configuration mode
7B1#          :PMtx drop to config mode 1
7B0#          :JSMtx PMtx drop to config mode 0 --- ends capability
```

PARAMETER EXCHANGE frames:

```
78M#2P810000Xx00Vv00:JSMtx check if pointer Xx sub Vv exists
79M#4P8100000000000000:PMtx yes, pointer exists
79M#CP8100000000000000:PMtx no, pointer does not exist
79M#2P8C0000asciitxt:PMtx text chunk used for cJSM display messages. Only prese
78M#4P8F00000000000000:JSMtx request "pointer" from PM. Pointer address set with 78M#2P81...
79M#2P8F0000XxYy0000:JSMtx XxYy = "pointer" returned by PM. Response to 78M#408F000000000000
79M#C181000028000000:PMtx Error: address not found.
78M#208000001M000000:JSMtx programming header issued prior to capability
```

SERIAL NUMBER enumeration/confirmation:

```
1FRSTtUu#          :JSMtx/rx PMtx/rx SerialNumber exchange. R=Subsequence
1f0000Y-#
```

Play video2.mp4

POC demo @ SSD Jul '16

SmartWheels

[EECS 149/249A Class Project]

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Corten Singer
cortensinger@berkeley.edu

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Department of Electrical Engineering and Computer Science
University of California
Berkeley, CA

ABSTRACT

We develop a self-driving, target-following, obstacle-avoiding wheelchair and discuss the design considerations that were incorporated into the creative process. We use a Raspberry Pi 3 Model B with a PiCAN 2 shield to send commands to the wheelchair via the R-net protocol. An iPhone application is used to track AprilTags (2D barcodes developed for robotics applications) with its camera and send data to the Raspberry Pi. Finally, we use three ultrasonic sensors attached to the Raspberry Pi to detect obstacles.



control of his wheelchair. He was eager to share his research [6] with us and help us gain access into our wheelchair's control system. He was also the motivation behind the features we wanted to implement in our smart wheelchair. Stephen suffers from bilateral open-cleft schizencephaly, a rare brain condition that leaves him non-verbal and paralyzed except for one hand. Thus, Stephen cannot speak and navigate simultaneously. Our solution allows Stephen to let his wheelchair autonomously follow his friends while avoiding obstacles so that he can participate in conversation without the burden of stopping each time he wants to contribute. Further, our intelligent wheelchair design has incredible potential for visually impaired wheelchair users who have trouble navigating in unfamiliar terrain. Globally, there are 39 million blind people and 246 million have low vision [5]. It is estimated that 1 in 10 visually impaired

Play video3.mp4

SmartWheels Demo

What about a
headline grabbing
remote exploit
without modifications
to the chair?

The only R-net wireless device



The R-net Family

BT-MOUSE
D51111.03
BP12060172
PG DRIVES TECHNOLOGY LTD
MADE IN ENGLAND

Mouse
module



“iDevice”
module



9S12C

LED JSMs



Monochrome JSMs



ARM7

Color JSMs



Toggles & Pots



Omni

EL PM90



80(90)



5

Seating Module

MC908 +
56F83 DSP



PM80/120



2L
4L
6L

Intelligent Seating/
Lighting Module



Encoder Module



2
4
6

Intelligent Seating
Module

XC164 Infineon



Lighting Module

MC908GZ



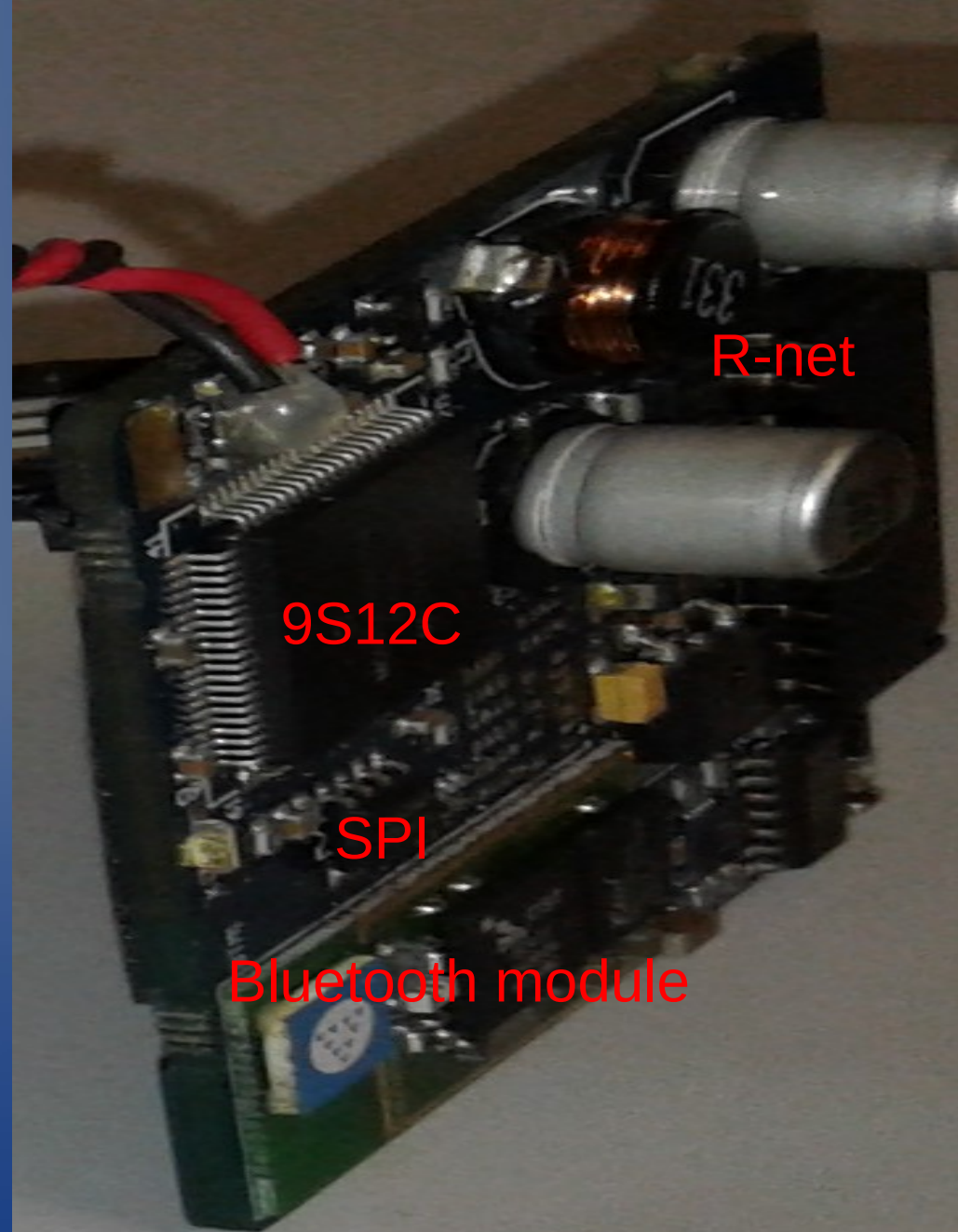
Output Module

9S12C

Bluetooth Module



R-net Bluetooth Mouse Internals



Google Image search: "MC9S12"

some interesting results





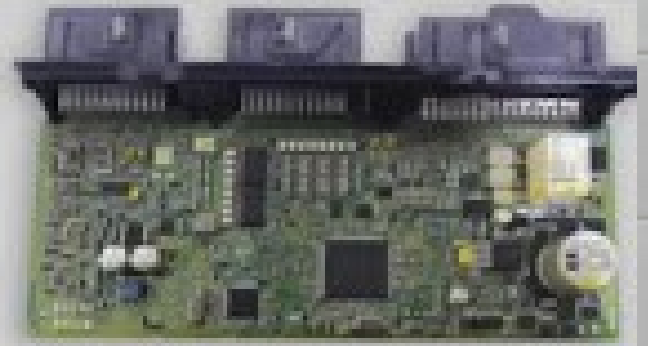
Производитель: КНР
Модель: Xprog-M 5.55
Наличие: В магазине. Отправим за 24 часа

8 230 р. или

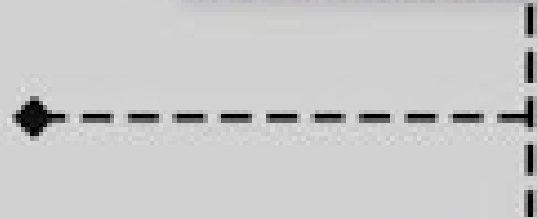
WTF IS GOING ON HERE?

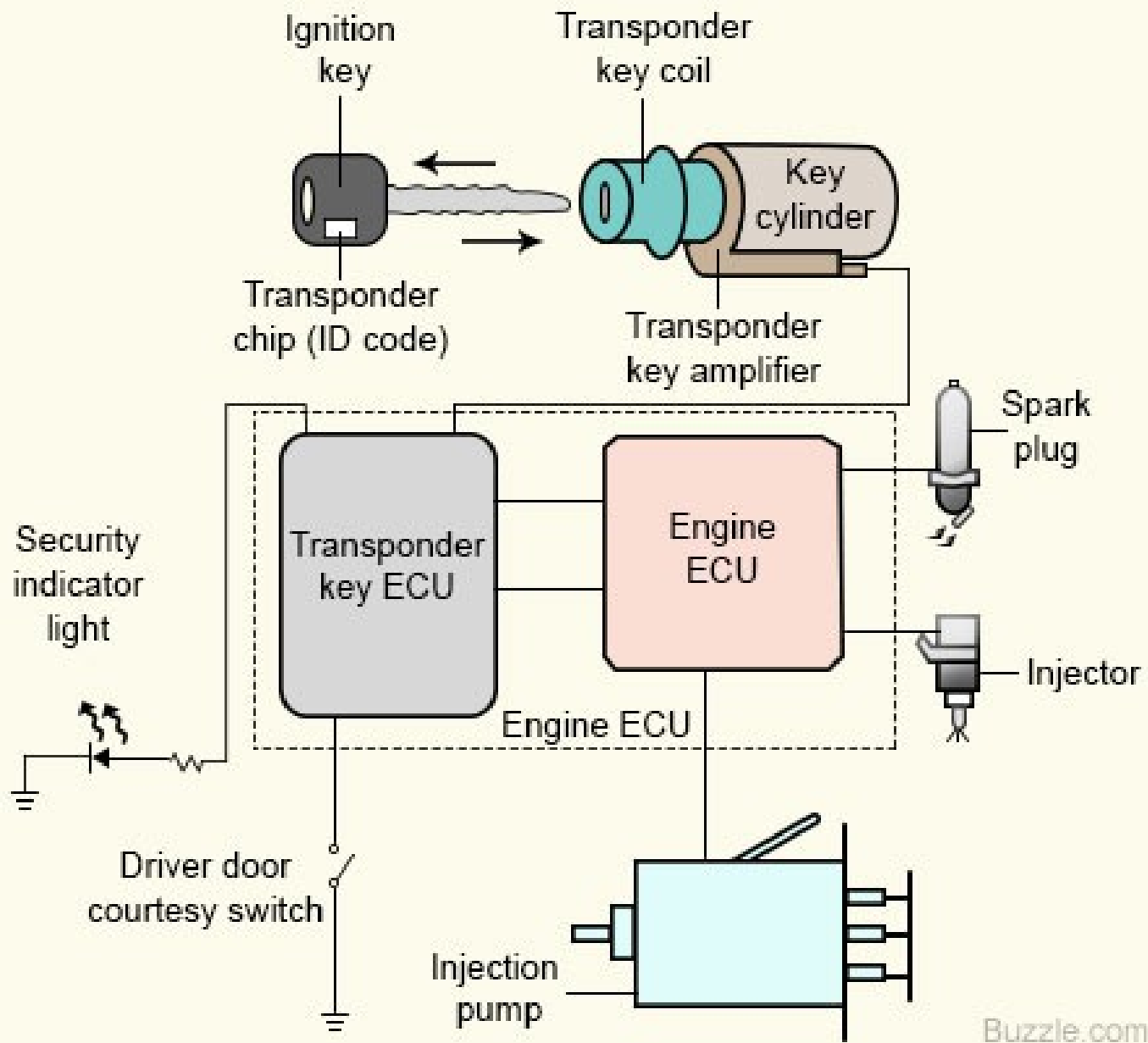






CAS4





Send ECU + \$\$ = Get FLASH



BMW CAS4 READING SERVICE 100% SUCCESS

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We can read data flash & program flash & will send you files to make key
if your an auto locksmith**

**Or we can send it back with info changed to what you need for dash correction
(If you want cluster doing too send me eeprom or eeprom data
and i can change for you at extra cost)**

**We will test it first on bench then afterwards before shipping
Please only send ones that have not been attempted to read first
or you will be charged to test it & if it fails will be charged for return postage .**

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special delivery return postage**

Any info contact Anthony on 077707 23332

Thanks for looking

Does not lift
legs of mcu.

Clock injected
at component



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IC reverse analysis research
 Removing read protection
 IC code extraction
 IC decryption

MCU CPLD FPGA ARM DSP....

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ST Unveils World's First ARM ...

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> The general method of decryption chip

FAQ:

- > IC to decrypt the law relating to reputation
- > With regard to the process of IC Crack Service
- > How to contact us?
- > We are able to provide those services?

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[atmega2560](#) [atmega8515L](#) [atmega8535L](#) [atmega88V](#) [atmega48V](#)
- [atmega128L](#) [atmega64L](#) [atmega32L](#) [atmega16L](#)more
- ATtiny> [ATtiny45](#) [ATtiny88v](#) [ATtiny13](#) [ATtiny24V](#) [ATtiny15L](#)
[ATtiny11L](#) [attiny13](#)more

CPLD Crack & FPGA Crack

- altera> [EPM3512A](#) [EPM3256A](#) [EPM3128A](#) [EPM3064A](#) [EPM3032A](#)
[EPM7128SLC](#) [EPM7064SLC](#) [EPM7032SLC](#)more
- Xilinx> [Xc95288XL](#) [Xc95144XL](#) [Xc9572XL](#) [Xc9536XL](#)more

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- SST > [SST89E52RD2](#) [SST89E52RD](#) [SST89E516RD2](#) [SST89E516RD](#)more

Send MCU = Get Firmware*

* or full refund. Chip is not returned :(

MCU crack services



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MCU crack unlock/SCM crack unlock PCB clone IC Programmer Service/FAQ IC unlock news

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Service Process:

- Please send an inquiry by email, what's IC MCU CHIP MODEL you have;
- Our staff will response 4-8 hours with quotation and deliverytime and conditions for service.

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- ◆ Break Copy Protection in MCU
- ◆ Atmel MCU Crack
- ◆ MICROCHIP MCU Attack
- ◆ CYPRESS MCU Attack
- ◆ Freescale IC Crack
- ◆ NXP IC Attack

Home IC unlock crack/IC Chip decryption

Home

Difficult chip decryption:

- ☑C8051 chip crack unlock
- ☑Samsung MCU unlock crack
- ☑STC_STC12C unlock
- ☑Cypress/Cy8c MCU crack
- ☑SPMC65 SPMC75
- ☑MSP430
- ☑CPLD un
- ☑ARM MCU
- ☑MASK Ro
- ☑DSP Chi
- ☑IC MCU Pro
- ☑Hilo Syst
- ☑Bee prog
- ☑EasiPro

The buyer is liar: (everyone take care and remember this liar)

Name:Lin
Address:via togni, 6, brescia, Brescia, Italy
Phone:00393333336633

The cheat bought goods then return back wrong and bad things to us.

CIRCUIT engineering

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ORANGE5

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Orange 5 base set- 350 EURO whitout including VAT

Additional Adapters for Orange 5

Additional Software for Orange 5

Technical Info

- USB power supply (USB2.0/3.0).
- Universal easy to plug panel ZIF16 for EEPROM
- Control of contacts in the sockets



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...issan, VW, Bmw

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CarProg manuals

CarProg
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Info Manuals

...sn: F10121c: AR0031211 CarProg serial



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Location: /CARPROG/Software/MCU

52.4 - CarProg Motorola (Freescale) 912 and 9S12 MPU programmer



Product Information

CarProg Motorola and Freescale 912 and 9S12 series MPU internal EEPROM programmer.

Supported MCUs:

- 912B32 (1H91F, 0J38M)
- 912B32 (3H91F)
- 912B32 (4J54E)
- 912B32 (9H91F)
- 912D60 (0K13J)
- 912D60 (0K75F)
- 912D60 (4F73K)
- 912DB128 (0L85D)
- 912DC128 (0K50E)
- 912DG128 (3K91D)
- 912DG128 (5H55W)
- 9S12H128 (1K78X)
- 9S12DB128 (0L85D)
- 9S12DG128 (1L59W)
- 9S12DG256B (1K79X)
- 9S12XDP512 (0L15Y)
- 9S12D64 (2L86D)
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Welcome to ELDB electronics store





Padelis Floudas

@ Edward Karpicz on Feb 5, 2014 1:30 PM

For urls on programmers that do bypass the security on these MCUs is following:

http://www.xprog-m.com/product.php?id_product=50

http://www.scorpio-lk.com/eng/orange5_main_eng.html

and at the bottom there is a "general recommendation":

http://www.eldb.eu/index.php?route=information/information&information_id=15

These tools are sold as vehicle tools many years now and they are worth the money. There are more tools that do the same thing like "UPA programmer".

The data that i have would be garbage if i reprogrammed the unit with those data and it wouldnt work. You could say that "how do you know that the data are erased?" and the discussion would go on for ever.

What is strange is that as an Electrical Engineer and programmer i cant understand how these tools bypass the security. This is why i started this discussion here. More brains work better than one. 😊

**“as an Electrical Engineer and programmer
*i cant understand how these tools bypass the security.***

This is why i started this discussion here.”



lama NP

@ Padelis Floudas on Feb 7, 2014 7:02 AM

Hi,

I hope you understand I will not continue with thinking how to hack the MCU.

Also to Edward:

First of all, there's absolutely no 100% secure application, micro, device, etc. If there's enough demand to "hack" something, it will be done. Just ask Microsoft and the XBOX, Apple and the iPhone or the DVD industry. Saying that our parts are 100% secure could be a lie. So, the answer on the question is really not important

DO NOT
CONNECT
THIS MACHINE
TO INTERNET

Recycle Bin

Universal XPROG software - V5.6.0

File Edit Search View Project Run Tools Options W

New Open Save As Copy Paste Read Write Verify

8-bit 16-bit 32-bit Lo-Hi

Type MCU/MPU Start 0x00000000
Device MC9S12C64-FLASH-secured Size 0x00010000
Brand Freescale HC(S)12

Session log file

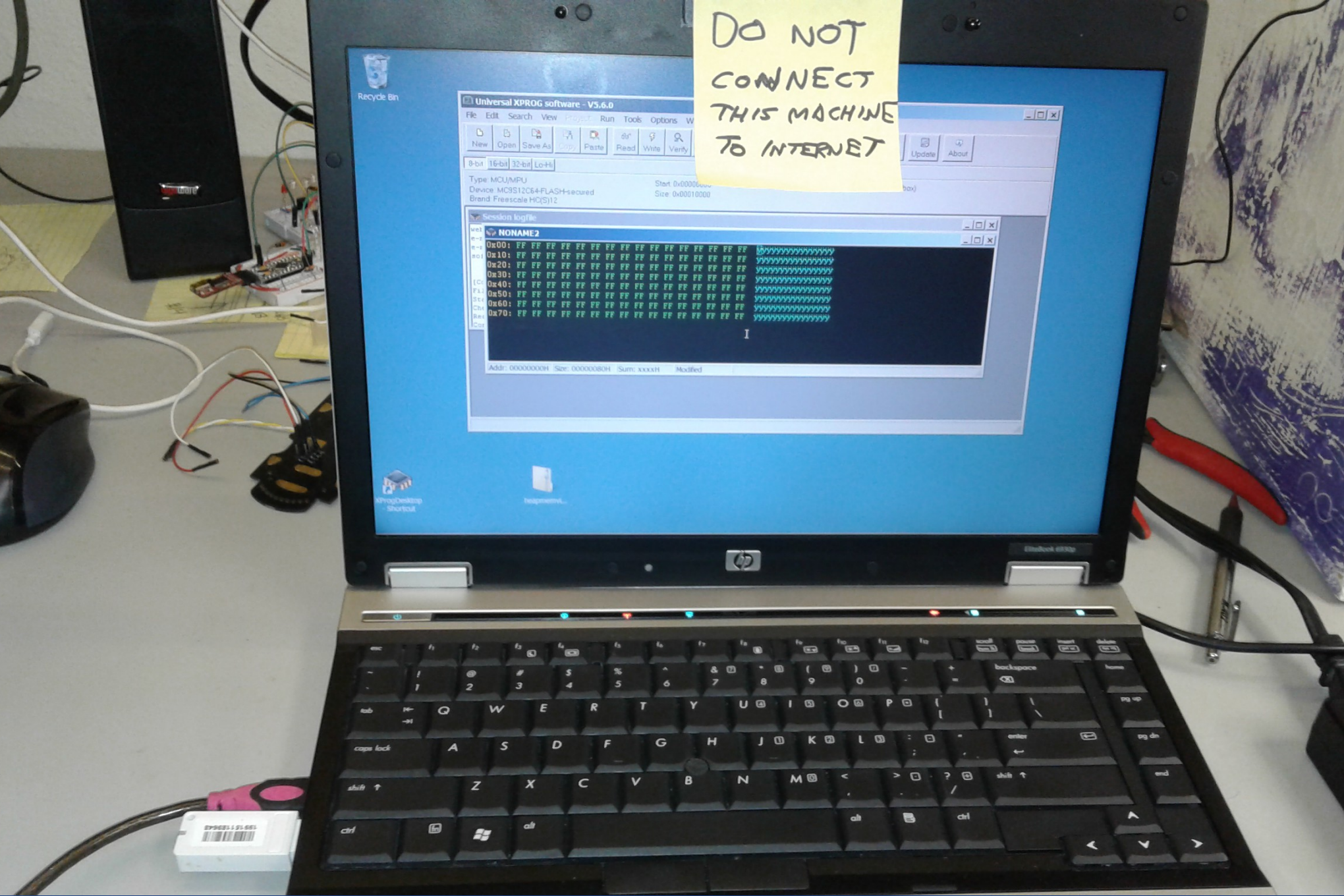
```
hex  
e-r  
no: 0x00: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF  
0x10: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF  
0x20: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF  
0x30: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF  
0x40: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF  
Fl: 0x50: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF  
St: 0x60: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF  
Ch: 0x70: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF  
Re:  
Co:
```

I

Addr: 00000000H Size: 00000800H Sum: xxxxx Modified

My Desktop Shortcut

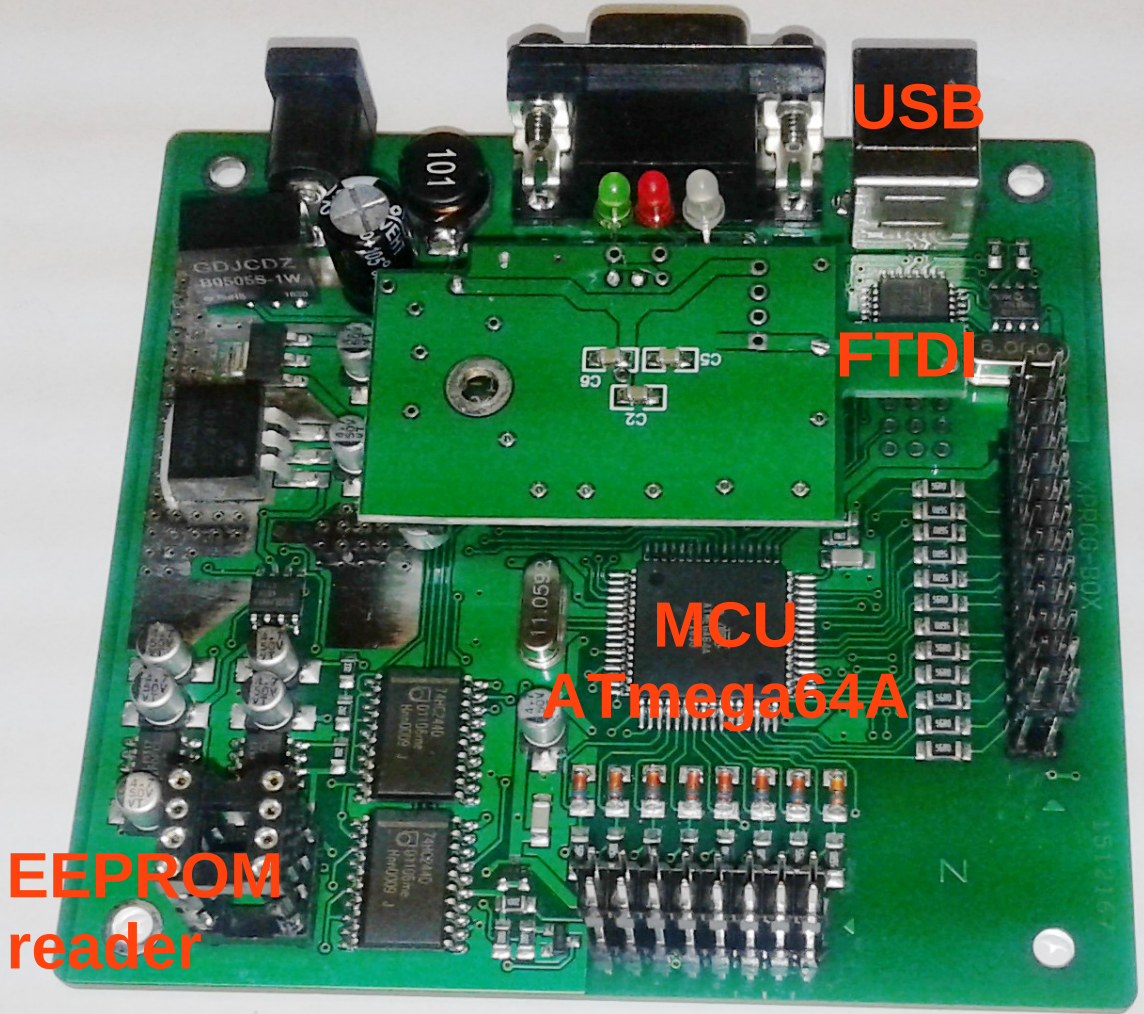
hsapromm...



Cracked Xprog software

Notice:

1. If your X-Prog is older version, cannot use this newest dongle to update to V5.60
2. Close all of the computer anti-software. If not, X-prog software may be killed.
3. **Disconnect the internet.** If not, the *internet may damage the hardware*.
4. Uninstall all the old xprog-m, or xprog box software, make sure that your PC only install our software for our xprog-box 5.70 , our xprog-box hardware cannot work with other lower or higher software. If not, the hardware will be damaged, and will lose its warranty...
5. **Never try to UPDATE**, the hardware will be damaged if you want to try to upgrade it online, without any warranty.
6. We cannot refund, cannot exchange, can not repair if you do not listen to those advices. It means that you accept those conditions if you have ordered our xprog-box.



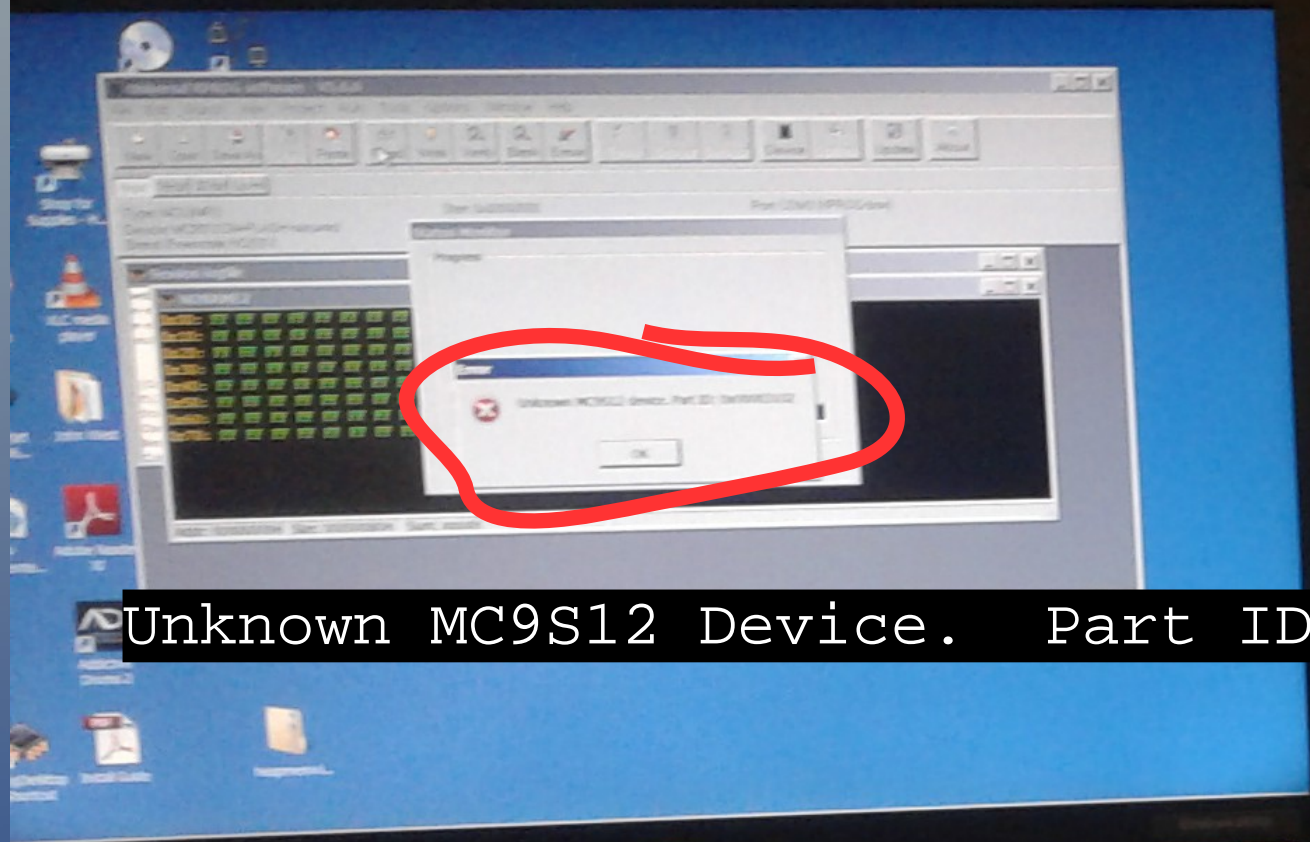
USB

Xprog
internals

FTDI

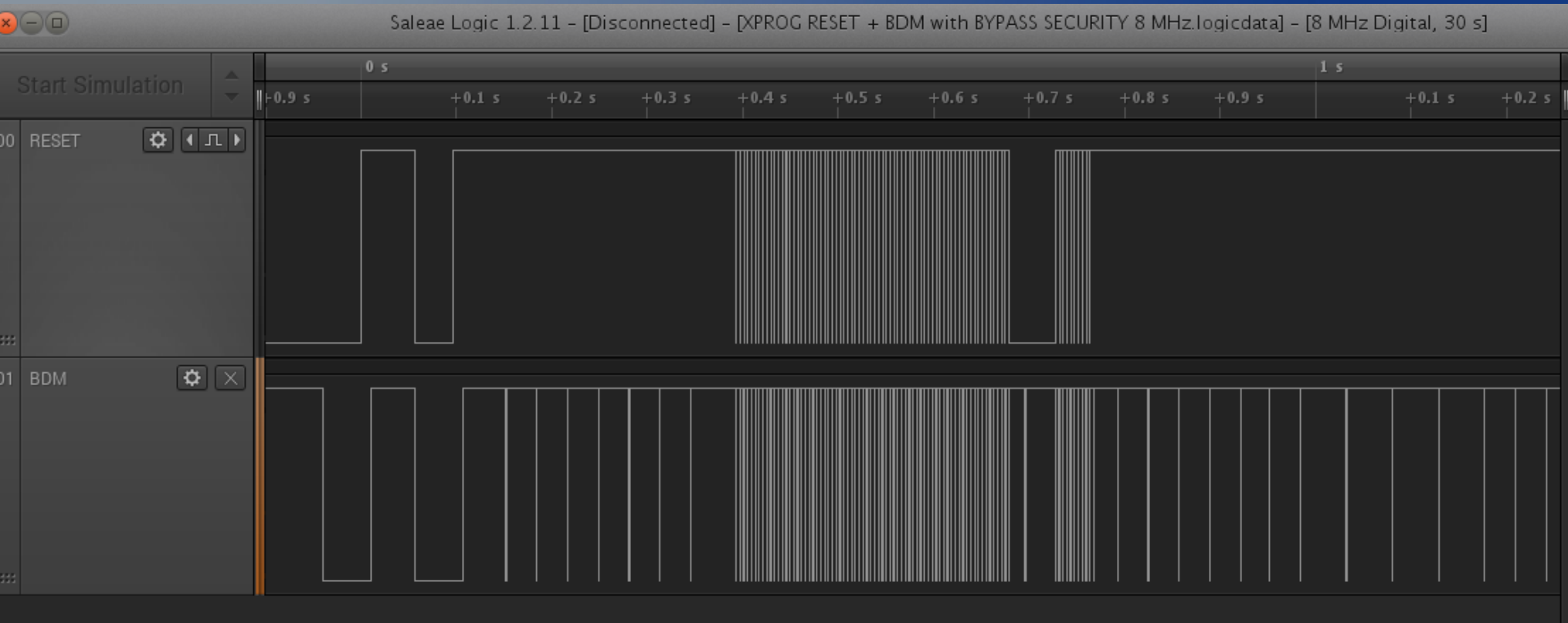
MCU
ATmega64A

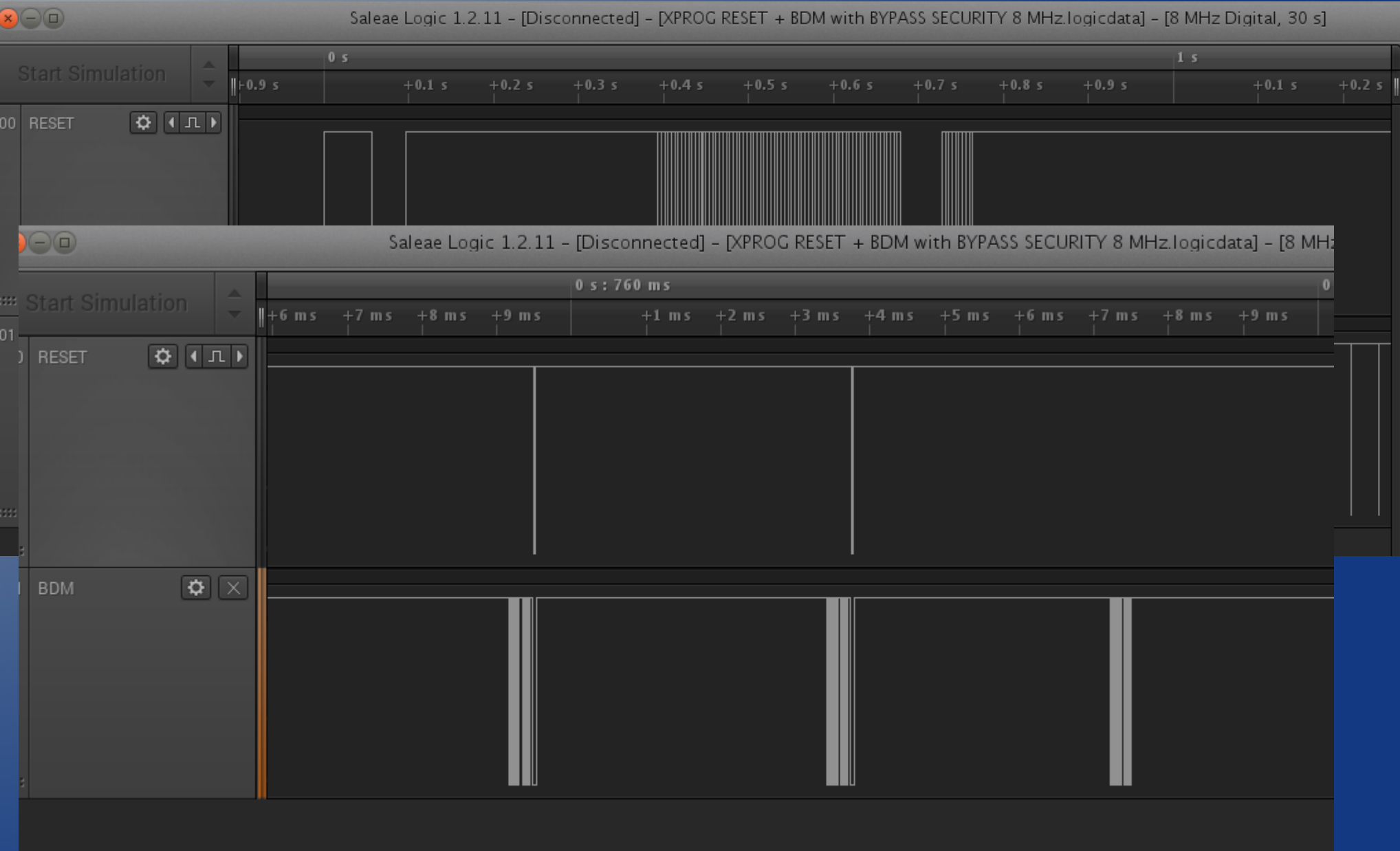
EEPROM
reader



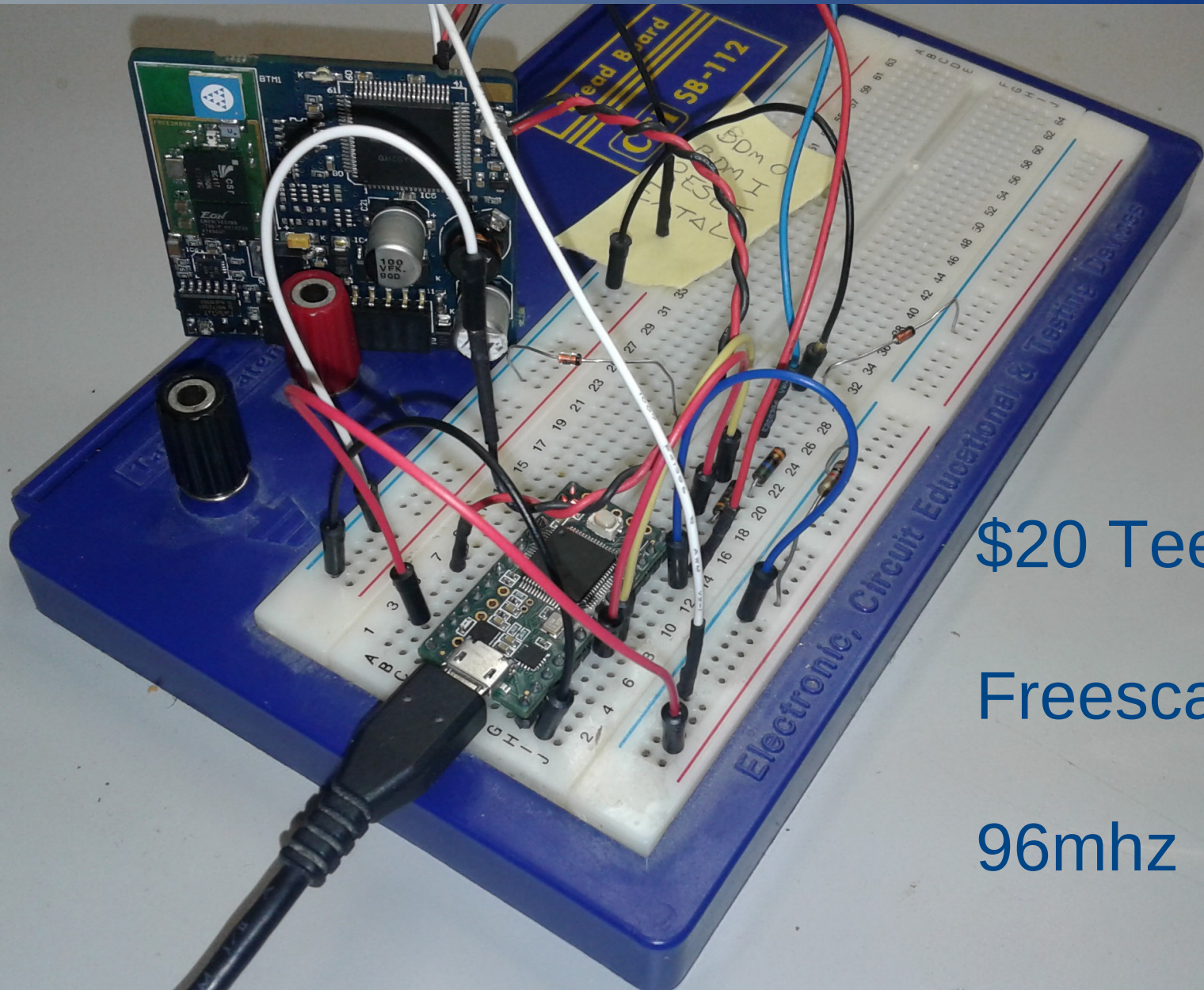
Unknown MC9S12 Device. Part ID: 0x00003102

GLITCHING THE HCS12 RESET-PHASE STATE MACHINE BY PULLING RESET HIGH AT CRITICAL POINTS





```
0.751430375 - 0.751430375 '0xe4ff01' READ_BD_BYTE FF01 = FFFF RSTGAP: 39143
0.751610625 - 0.751610625 '0xe4ff01' READ_BD_BYTE FF01 = FFFF SEC!=0
0.751762375 - 0.75178175 RESET 194
0.75513675 - 0.75513675 '0xe4ff01' READ_BD_BYTE FF01 = FFFF RSTGAP: 33550
0.755317 - 0.755317 '0xe4ff01' READ_BD_BYTE FF01 = FFFF SEC!=0
0.755468625 - 0.755488375 RESET 197
0.759162 - 0.759162 '0xe4ff01' READ_BD_BYTE FF01 = FFFF RSTGAP: 36736
0.75934225 - 0.75934225 '0xe4ff01' READ_BD_BYTE FF01 = FFFF SEC!=0
0.759494125 - 0.759513625 RESET 195
0.75951375 - 0.759513875 RESET 1
0.763426 - 0.763426 '0xe4ff01' READ_BD_BYTE FF01 = FFFF RSTGAP: 39121
0.76360625 - 0.76360625 '0xe4ff01' READ_BD_BYTE FF01 = FFFF SEC!=0
0.76375775 - 0.763777375 RESET 196
0.767221875 - 0.767221875 '0xe4ff01' READ_BD_BYTE FF01 = 00CA RSTGAP: 34445
0.767402125 - 0.767402125 '0xe4ff01' READ_BD_BYTE FF01 = 00CA SEC!=0
0.7922245 - 0.7922245 '0xe4ff01' READ_BD_BYTE FF01 = 00CA RSTGAP: 284471
0.79240475 - 0.79240475 '0xe4ff01' READ_BD_BYTE FF01 = 00CA SEC!=0
0.824448625 - 0.824448625 '0xe0ff0f' READ_BYTE FF0F = FFFC
0.856687625 - 0.856687625 '0xe00101' READ_BYTE 0101 = 00FC
0.8889145 - 0.8889145 '0xe0ff0d' READ_BYTE FF0D = FFFF
0.921142125 - 0.921142125 '0xe00104' READ_BYTE 0104 = FF00
0.951355875 - 0.951355875 '0xe00010' READ_BYTE 0010 = 0900
0.98358225 - 0.98358225 '0xc808001234' WRITE_WORD 0800 = 1234
1.031914625 - 1.031914625 '0xc808025a7a' WRITE_WORD 0802 = 5A7A
1.08026625 - 1.08026625 '0xe80800' READ_WORD 0800 = 1234
1.128606875 - 1.128606875 '0xe80802' READ_WORD 0802 = 5A7A
1.176947 - 1.176947 '0xe4ff01' READ_BD_BYTE FF01 = 00CA RSTGAP: 4131696
1.17712725 - 1.17712725 '0xe4ff01' READ_BD_BYTE FF01 = 00CA SEC!=0
1.209184875 - 1.209184875 '0xc4ff0100ca' WRITE_BD_BYTE FF01 = 00CA
1.24149775 - 1.24149775 '0xe00013' READ_BYTE 0013 = 0000
1.271623125 - 1.271623125 '0xe8001a' READ_WORD 001A = 3102
```



\$20 Teensy 3.2

Freescale K20

96mhz

Reading 9s12 after bypass security

```
0x0000C170 : FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF
0x0000C180 : FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF
0x0000C190 : FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF
0x0000C1A0 : FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF
0x0000C1B0 : FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF
0x0000C1C0 : FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF
0x0000C1D0 : FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF
0x0000C1E0 : FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF
0x0000C1F0 : FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF FFFF
```

65535

% gs

Target status reg => (0xC2) = ENBDM, BDACT UNSEC,

BDM status => Ackn, Speed-sync, Upp-Off, Uld-External, RSTO=1, No Reset, CFUX-ru

Speed = 3996 kHz (1922 ticks, sync=32.0 us)

% rw 0xc000 0x100

```
:rw =>
0x0000C000 : 37F6 36F4 7B33 1FF6 36F0 2612 F636 F126
0x0000C010 : 0DF6 36F2 2608 F636 F326 0379 331F 4A5F
0x0000C020 : ED00 0461 0379 331F E684 4A7F 9000 0441
0x0000C030 : 10E6 804A 7F90 0004 4107 C601 7B33 1C20
0x0000C040 : 0379 331C F633 1F27 1AB7 1012 B745 49C3
0x0000C050 : 1CC4 3BCC 0000 C901 8900 B746 3A11 7D33
0x0000C060 : 2320 05C7 877C 3323 320A 69AF E680 CE33
0x0000C070 : 0B69 E5CE 3303 69E5 6280 E680 C108 25EC
0x0000C080 : 7933 0179 3302 6980 E680 8759 B745 CD00
0x0000C090 : 006D E233 1362 80E6 80C1 0425 EB79 331B
0x0000C0A0 : 7933 1FC6 017B 331E 7933 1D79 3320 7933
0x0000C0B0 : 2279 3321 7933 1C7D 3323 877C 3327 7C33
0x0000C0C0 : 297B 3325 C605 7B33 26C6 037C 3329 7A33
0x0000C0D0 : 2B7A 332C 320A 69AF FE33 4927 1709 7E33
0x0000C0E0 : 4904 2504 C601 6B80 E680 0421 07CC 5550
0x0000C0F0 : 4AC1 1B00 320A 201A F633 4C87 C333 4D4A
0x0000C100 : C11B 00F6 334C C101 2405 7233 4C20 0379
0x0000C110 : 334C F633 4BF1 334C 26DE 0A3B B745 E600
0x0000C120 : 6B80 C601 6B81 B633 4818 178C 201A 201A
```


MCUs on PowerWheelchair

Power Module – Freescale MC56F83

Joystick Module – NXP LH75411-NOQ
32-BIT ARM7

IO module – Freescale MC908GZ

Bluetooth “iDevice” - Freescale 9S12C

Light Module (not OEM) -
SAF-XC164CS
ATMEL AT90Can128



; ===== S U B R O U T I N E =====

; exit if CAN rx not full

get_CAN_ID:

```
brclr  CAN0RFLG,#1,no_CAN_RXF ; CODE XREF: seg000:0000429Afp
brset  CAN0RIDR1,#8,get_CAN_extended_ID ; Extended: ID20 ID19 ID18 SRR=1 IDE=1 ID17 ID16 ID15
bsr    mung_CANMSB_into_X ; X = 00000 ID10 ID9 ID8 / ID7 ID5 ID6 ID4 ID3 ID2 ID1 ID0
      ; X = 00000 ID28 ID27 ID26 / ID25 ID24 ID23 ID22 ID21 ID20 ID19 ID18
stx    CANRIDtop11 ; EXT RTR 0 0 0 ID28/10 ID27/9 ID26/8 ID25/7 ID24/6 ID23/5 ID22/4 ID21/3 ID20/2 ID19/1 ID18/0
brclr  CAN0RIDR1,#$10,not_RTR ; Extended: ID20 ID19 ID18 SRR=1 IDE=1 ID17 ID16 ID15
bra    was_RTR ; set RTR bit in buffer
```

; -----

get_CAN_extended_ID:

```
bsr    mung_CANMSB_into_X ; CODE XREF: get_CAN_ID+5fj
      ; X = 00000 ID10 ID9 ID8 / ID7 ID5 ID6 ID4 ID3 ID2 ID1 ID0
      ; X = 00000 ID28 ID27 ID26 / ID25 ID24 ID23 ID22 ID21 ID20 ID19 ID18

tfr    x,d
oraa   #$80 ; 'C' ; set EXTENDED_FRAME bit in D
std    CANRIDtop11 ; EXT RTR 0 0 0 ID28/10 ID27/9 ID26/8 ID25/7 ID24/6 ID23/5 ID22/4 ID21/3 ID20/2 ID19/1 ID18/0
ldab   CAN0RIDR1 ; Extended: ID20 ID19 ID18 SRR=1 IDE=1 ID17 ID16 ID15
lsrb
andb   #3 ; B = ID17 ID16
stab   CANbuf_RX_XID_17to16 ; ID17 ID16
ldab   CAN0RIDR2 ; ID14 ID13 ID12 ID11 ID10 ID9 ID8 ID7
lsrb   ; B = 0 ID14 ID13 ID12 ID11 ID10 ID9 ID8
ldaa   CAN0RIDR1 ; Extended: ID20 ID19 ID18 SRR=1 IDE=1 ID17 ID16 ID15
      ; Standard: ID2 ID1 ID0 RTR IDE=0 0 0 0
pshb
ldab   #$80 ; 'C' ; << 7
mul    ; B = ID15 0 0 0 0 0 0 0
orab   0,sp
stab   CANbuf_RX_XID_15to8 ; ID15 ID14 ID13 ID12 ID11 ID10 ID9 ID8
ldab   CAN0RIDR3 ; ID6 ID5 ID4 ID3 ID2 ID1 ID0 RTR
lsrb   ; drop RTR bit
ldaa   CAN0RIDR2 ; ID14 ID13 ID12 ID11 ID10 ID9 ID8 ID7
stab   0,sp
ldab   #$80 ; 'C'
mul    ; B = ID7 0 0 0 0 0 0 0
orab   1,sp+
stab   CANbuf_RX_XID_7to0 ; ID7 ID6 ID5 ID4 ID3 ID2 ID1 ID0
brclr  CAN0RIDR3,#1,not_RTR ; check RTR
```



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